

# Keshav Bagri

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## SUMMARY

Experienced graduate student interested in applications of controls, AI, & optimization for vehicle dynamics and safety

## EDUCATION

### The Ohio State University

Master of Science in Mechanical Engineering [GPA: 4.0/4.0]  
Graduate Specialization in Automotive Systems and Mobility

Columbus, OH  
Aug'22 – May'24 (Expected)

### Indian Institute of Technology Kharagpur

Bachelor of Technology (Hons.) in Mechanical Engineering [GPA: 9.26/10]  
Micro Specialization in Embedded Control, Software, Modelling and Design [GPA: 9.5/10]

Kharagpur, India  
July'18 – May'22

## PUBLICATIONS

(accepted) Y. Singh, **K. Bagri**, A. Jayakumar, G. Rizzoni, *Fault Diagnostics for Oscillatory Failure Case in Aircraft Elevator Servos*, IFAC-PapersOnLine

## TECHNICAL SKILLS

**Programming:** C/C++, Git, Python, MATLAB, LaTeX, Arduino, ROS, Atmel Studio

**Softwares:** SOLIDWORKS, Ansys, MATLAB/Simulink, CARLA Simulator, Gazebo

**Libraries:** NumPy, SciPy, Pillow, SymPy, Matplotlib, OpenCV, TensorFlow, Keras, PyTorch, CARLA

## AWARDS AND ACHIEVEMENTS

- **Gold Medal** in Inter IIT Tech Meet 10.0 (2022) in the event “Powered Bonnet for EVs” by Jaguar Land Rover India
- **1st** place in Combustion category & Engineering Design among **31 teams** globally at Formula Bharat Virtuals 2021-22
- **Gold Medal** in Inter IIT Tech Meet 9.0 (2021) in the event “Bosch’s Electric Vehicle Simulation” by Robert Bosch India
- **5th** place in Formula Student Electric Vehicle Concept Challenge 2020 among **37 teams** internationally by **Ather Energy**

## PROFESSIONAL EXPERIENCE

### The Ohio State University

Graduate Teaching Associate | Department of Mechanical & Aerospace Engineering

Columbus, OH  
Jan'23 – May'23

- Courses: [ME 3751: Kinematics and Mechanisms Design] | [ME 3670: Design and Analysis of Machine Elements I]
- Conducted recitation sessions for a batch of 40 students to discuss numerical & conceptual problems on a weekly basis

### Revolute Robotics

Controls Engineer | [\[Website\]](#)

Tucson, AZ  
Mar'22 – July'22

- Modified the **min. jerk trajectory** planner for smooth navigation using a dynamic window of 3 waypoints per time step
- Formulated the cost-based **path planning & obstacle avoidance** approach using min. jerk planner & A\* search algorithm
- Identified multiple methods to enable **data-logging over cloud** from the flight controller thus reducing manual intervention

### KPIT Technologies Ltd.

Summer Intern, CTO – Deep Learning

Pune, India  
May'21 – July'21

- Worked on the comparison between compilers & DL frameworks using pre-trained models for **performance analysis**
- Generated **deployable executables** using AI compilers like TVM, Glow to substantially reduce memory & inference time
- Developed a consolidated method of **hardware-specific** deployment of DL models used in automotive applications

### Ati Motors

SLAM Intern, Autonomy Team | [\[Website\]](#)

Bengaluru, India  
Nov'20 – Jan'21

- Studied the **OctoMap** mapping and implemented open-source datasets to facilitate better visualization of 3D maps
- Explored multiple **SLAM algorithms** like IMLS, EKF, Gmapping, etc. to select an efficient method for implementation
- Implemented the **Particle Filter** SLAM algorithm to build maps on a 2D grid using lidar and wheel odometry in Python
- Analysed the effects of multiple **resampling algorithms** and variation in **hyperparameters** on the map's quality

## RESEARCH EXPERIENCE

### Buckeye AutoDrive (SAE AutoDrive Challenge II)

Co-Captain | Co-Lead, Planning & Controls team

Columbus, OH  
Aug'22 – Present

- Currently working on establishing a **Hardware-in-Loop** testing setup by deploying the controller on the target hardware
- Developed the **behavioral planning** module for decision-making & maneuvering using Stateflow for a **level 4 autonomous vehicle** considering multiple possible scenarios and safety requirements
- Formulated the logic for **lane changing maneuver** in a highway setup & performed simulation-based testing for the same

## Warwick Manufacturing Group, University of Warwick

Research Collaborator, Verification and Validation Team | [[Website](#)]

Coventry, UK

Jan'22 – July'22

- Developed the Java-based translation framework between levels of **Scenario Description Language** for ADS simulation
- Formulated the mapping between environmental features and language variables using the taxonomy from **PAS 1883**
- Defined the **boundary conditions** for the agents' maneuver to describe the **Synchronised Serial Maneuver Sequences**

## OSU Centre for Automotive Research

Undergraduate Research Assistant, Driver Dynamics Lab | [[CAR](#)]

Columbus, OH

Feb'21 – Mar'22

- Worked on the validation of **IMU data** collected from different locations using physics-based transformation & noise filtering
- Proposed the **testing methodology** for the simulator's platform's motion and analysed the results in essence of the OMCT
- Utilized the output of **LVDTs** for multiple displacement inputs to compute the platform's **roll & pitch** angles in MATLAB

## Indian Institute of Technology, Bombay

Research Intern, Autonomous Robots and Multi-robot Systems Lab | [[Website](#)]

Mumbai, India

July'20 – Oct'20

- Formulated the **Markov Decision Process** representation of the scenarios considering different state and action spaces
- Generated training datasets for a **RL model** for the safe traversal of an autonomous vehicle in a **campus-like environment**
- Developed a **Finite State Machine** for lane following & 2-way lane intersection (without traffic signals) management

## Powertrain Development for Formula Student prototype | [[TeamKART](#)]

Supervisor: Dr. Dhananjay Kumar Srivastava, Department of Mechanical Engineering

IIT Kharagpur

June'19 – Aug'21

- Worked on the design of a custom **reactive muffler** for noise reduction from a vehicle, with an insertion loss of **25 dB**
- Designed the **fuel tank** and the mounting arrangement for the vehicle considering the optimal capacity requirement
- Designed and analyzed the components of the **transmission** and **cooling system** for a standard FSAE electric vehicle
- Engineered the **intake manifold & crossflow radiator** for a single cylinder engine, producing a power output of **35 HP**

## Fault Tolerant Control System for Electric Vehicles | [[Bachelor's Thesis Project](#)]

Supervisor: Dr. Somnath Sengupta, Advanced Technology Development Center

IIT Kharagpur

Feb'21 – Apr'22

- Prepared the complete **electro-mechanical** model for a 4WD EV for analysing the effect of faults & the control strategy
- Worked on the modeling of integrated **ABS & regenerative braking** for efficient braking & max energy recuperation
- Developed a non-linear **state estimator** using equations for vehicle dynamics to produce reliable estimates of vehicle's states
- Designed a novel **constraint-aware PI - sliding mode controller** for regulating the stability under all driving conditions
- Explored the possibility of integrating the novel controller with **reconfigurable control allocator** for fault tolerant control

## Self-driving Cars Specialization, Coursera

Supervisors: Prof. Steven Waslander and Prof Jonathan Kelly

University of Toronto

Apr'20 – June'20

- Implemented & tested control algorithms like **LQR, PID, Stanley, Pure Pursuit & MPC** for autonomous vehicle control
- Designed an **EKF** for state estimation & localization of an autonomous vehicle using **IMU, GPS & LIDAR** sensor data
- Estimated the **drivable space, lane** and **distance to obstacles** using the segmented image from a **CNN model**
- Developed the **behavioral & local planners** to generate a collision-free path, using **conformal lattice planning**

## LEADERSHIP

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### Co-Captain

Buckeye AutoDrive, SAE AutoDrive Challenge II

The Ohio State University

Sept'22 – Present

- Assisting the captain & faculty advisors in the project's activities and managing the **competition deliverables** & deadlines
- Coordinating with safety, controls, CAN, and perception teams to establish the **overall pipeline** on the system-level

### Deputy Team Leader

TeamKART, Formula SAE

IIT Kharagpur

July'20 – Aug'21

- Spearheaded a dedicated team of **47** students towards the research & development of Formula Student prototype vehicle
- Responsible for the project management & sponsorship initiatives to ensure the timely completion of the team's preset targets
- Prepared the design & manufacturing timeline and procurement plan to ensure a smooth & efficient workflow for project **K6**

### Powertrain & Corporate Relations Team Member

TeamKART, Formula SAE

IIT Kharagpur

July'19 – July'20

- Responsible for the design, analysis, and testing of the powertrain components in the FSAE prototype vehicle
- Involved in the training of **30** freshmen in basic automotive engineering, powertrain technology, and aspects of manufacturing
- Acquired monetary as well as technical sponsorships worth **INR 1,10,000** for the season 2019-20